



Ifremer

# TECHNOLOGICAL INNOVATIONS

## CHALLENGING PROFILING FLOATS CAPABILITIES

7th Euro-Argo Science Meeting  
Athens

Presented by Xavier ANDRÉ  
23 October 2019

# Plan

## 7<sup>th</sup> EURO-ARGO SCIENCE MEETING

ATHENS

22-23 OCT 2019



**Platforms from head to toes**



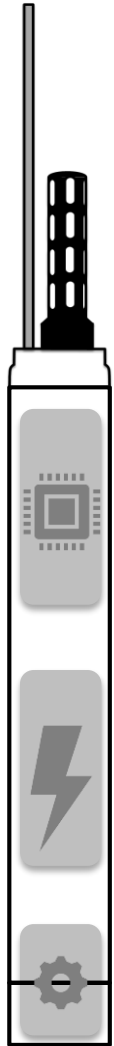
**Applications**



**Conclusion**

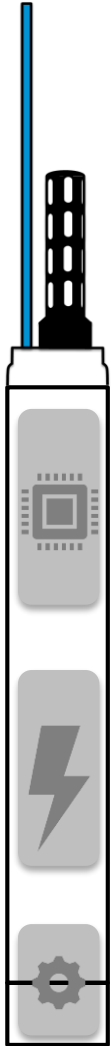


# From head to toes



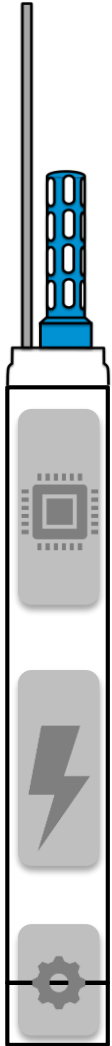
# From head to toes

## Transmissions



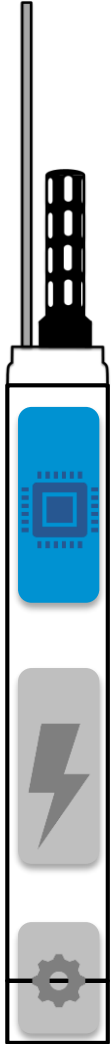
# From head to toes

CTD

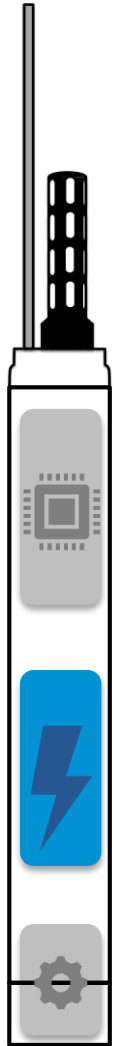


# From head to toes

Hardware & software



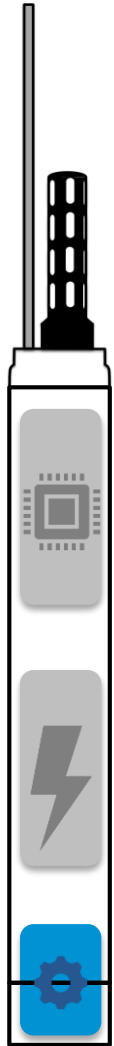
# From head to toes



Batteries



# From head to toes



Hydraulic system





# Transmissions

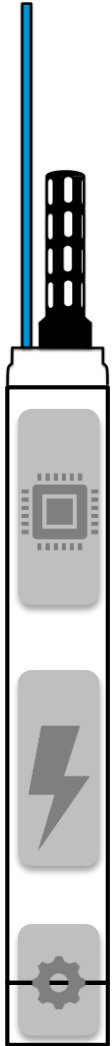
## Argos vs. Iridium



72\* % of the fleet

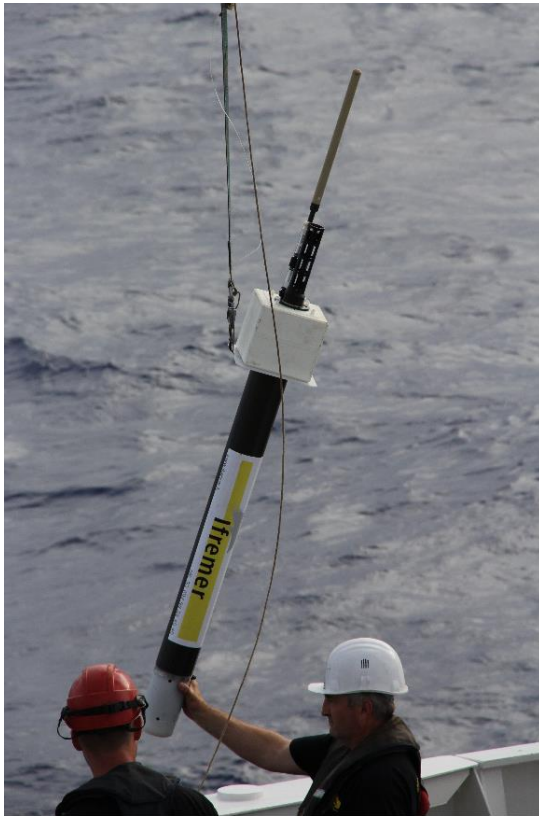


Argos-2



# Transmissions

## Argos-3/4 & Kineis



Arvor Argos-3  
© Ifremer

## Iridium Next



## Internet everywhere



# CTD

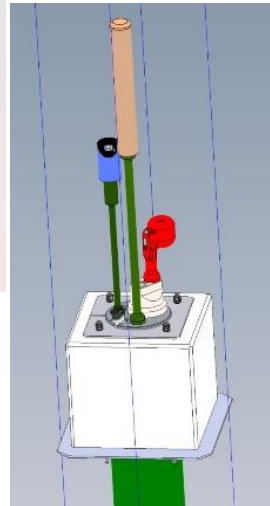
## RBR CTD



TWR APEX  
© RBR



MRV Alamo  
© RBR



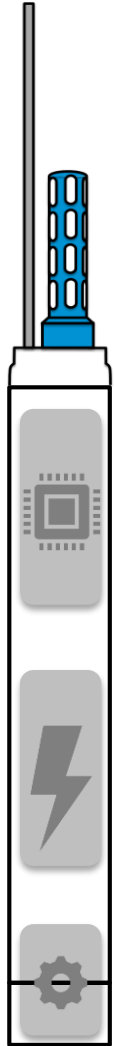
Arvor  
© Ifremer

## NOSS density sensor



Provior NOSS  
© nke instrumentation





Surface measurements

■ Risk: biofouling of sensor

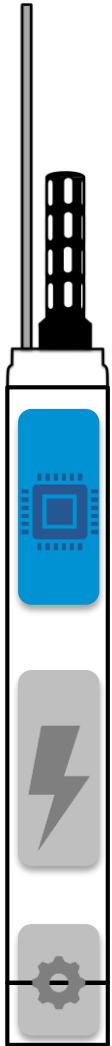
Bottom measurements

■ Systematic grounding



## ■ Embedded intelligence

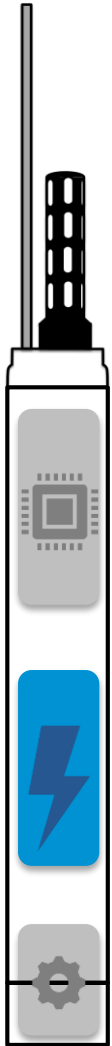
- Artificial intelligence & machine learning
- Hardware capacity!



# Batteries

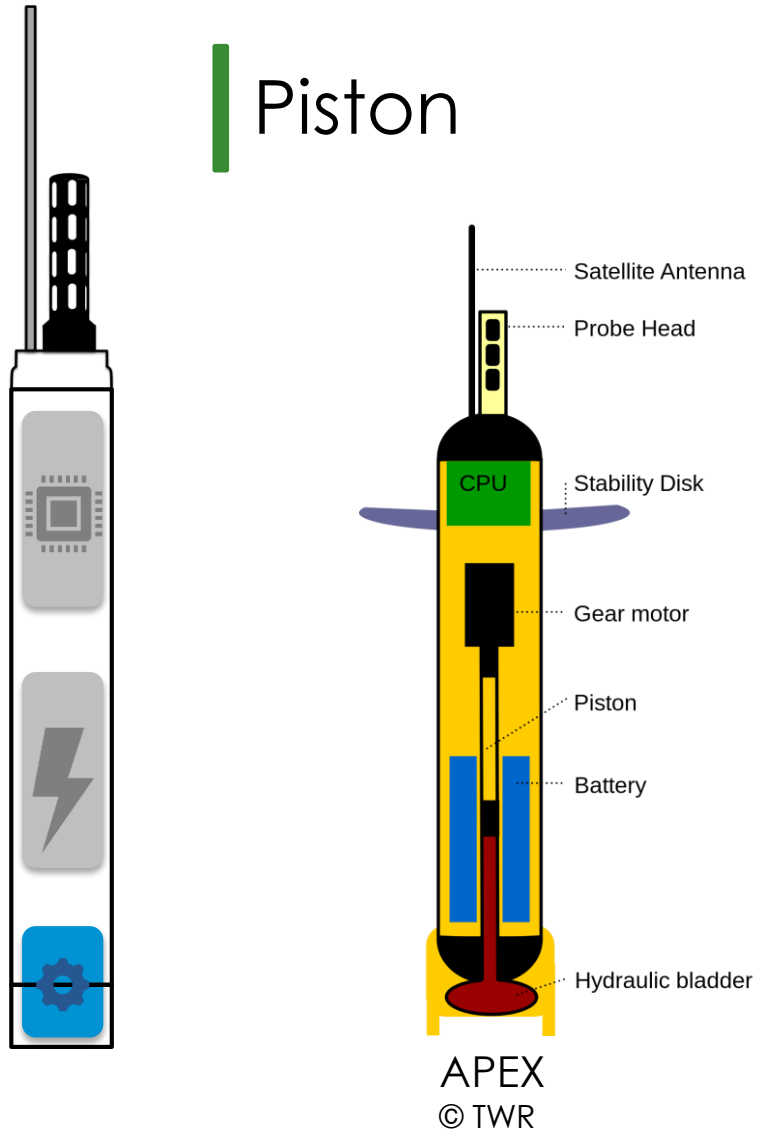
Life extension

- Tadiran on APEX & SOLO
- Energy recovery ?

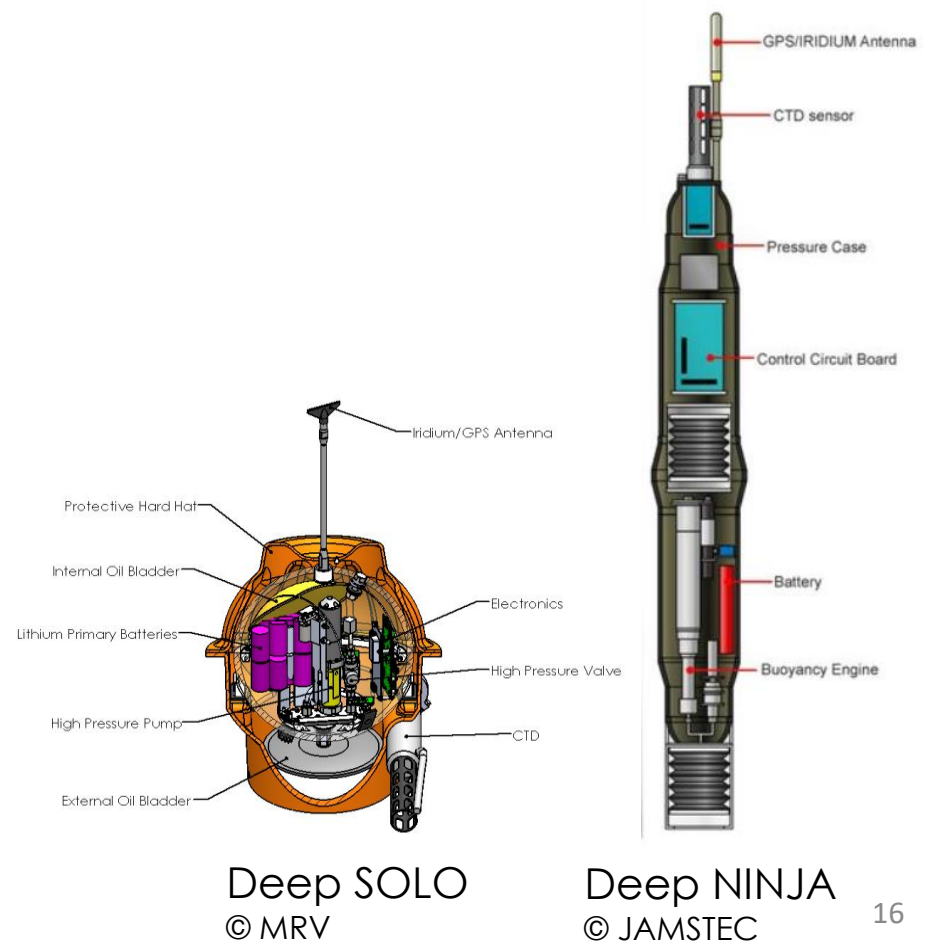


# Hydraulic systems

## Piston



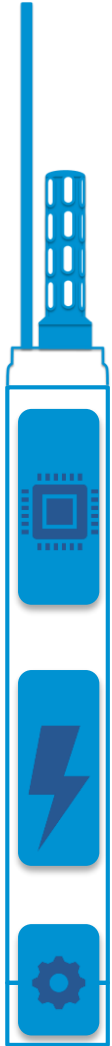
## Pump & valve



# Environmental impact

## Pollution due to profiling floats

- Less polluting materials
- Recovery





# Plan

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Platforms from head to toes



Applications



Conclusion



# Deep-Argo

## Sphere



Deep APEX



Deep SOLO

## Cylindar



Deep Arvor



Deep Ninja  
© TSC



# BGC-Argo

Up to 6 external sensors

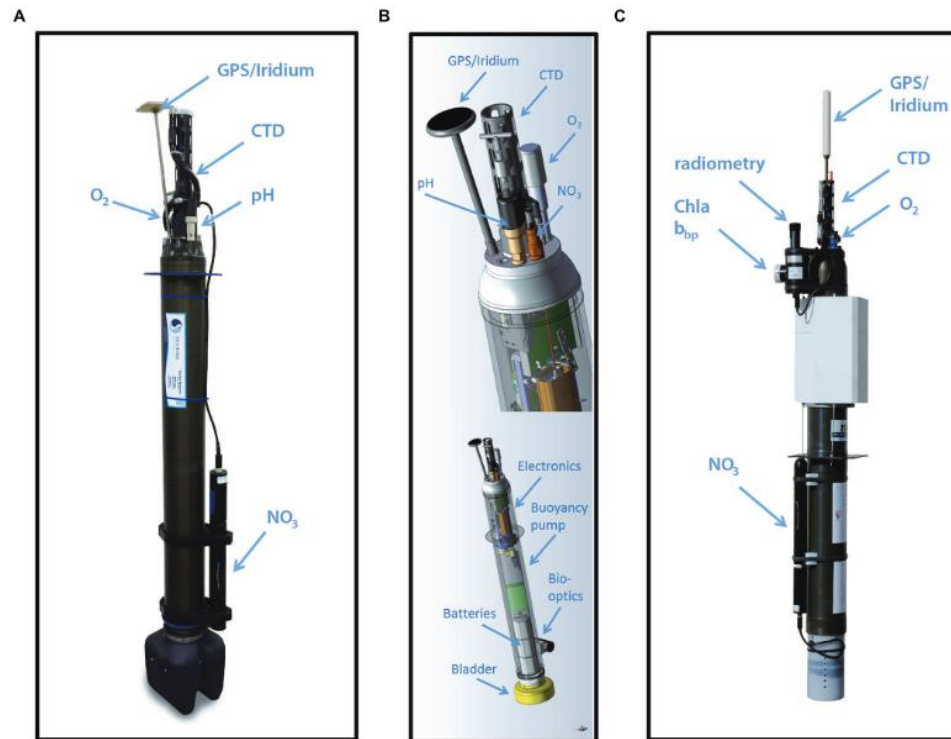


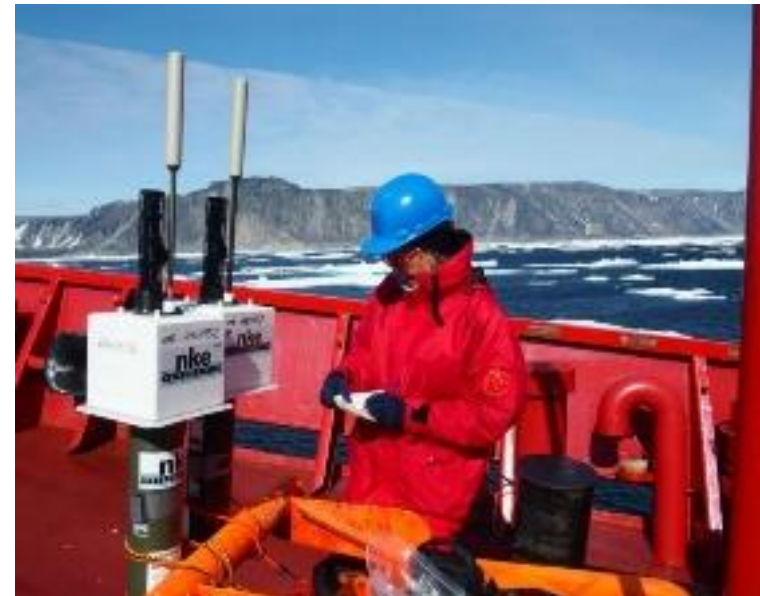
FIGURE 1 | The three main models of BGC-Argo floats presently in use include (A) Navis, (B) APEX, and (C) PROVOR.



# Polar-Argo

## Ice detection

- >45,000\* profiles
- Bi-di transmissions
- Ice Sensing Algorithm  
or Upward Looking Sonar
- Challenge:  
better location under ice



© Takuvik





# Specific developments

## Comparison platforms

### ■ SBE61 – SBE41 – RBR concerto

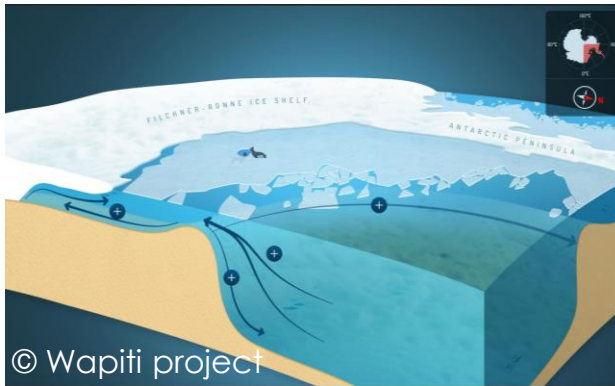


3-heads deep-Arvor  
© Ifremer



# Specific developments

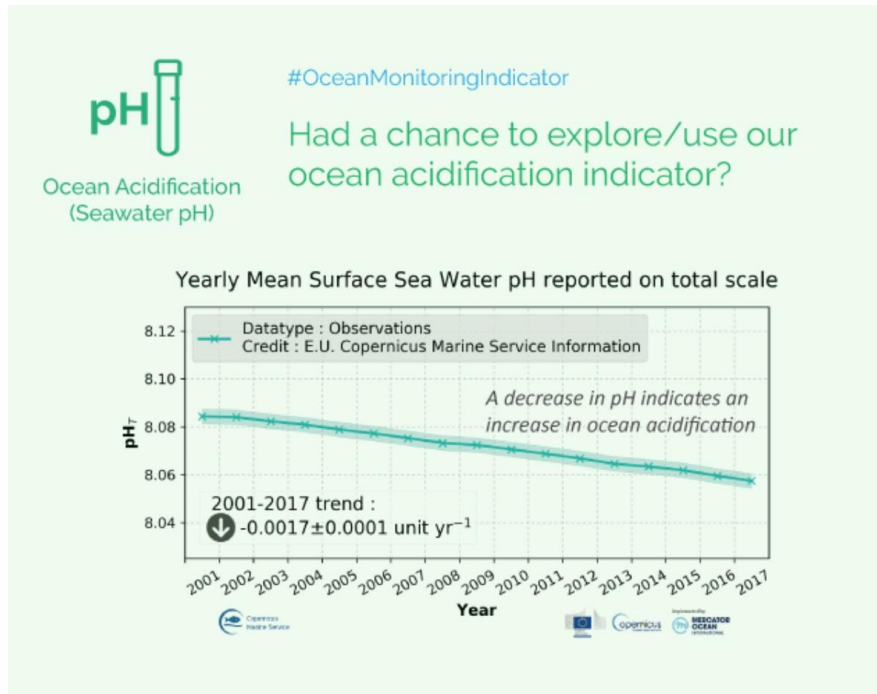
## Deep additional sensors



ADCP deep-Arvor  
© Ifremer

# New challenges

pH



Source: Copernicus Marine Service Ocean Monitoring Indicator (OMI).

pCO<sub>2</sub>



© Emilie Diamond





# Plan

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# Conclusion

## Technology

should adapt to the **science** needs,  
and not the contrary!





## Deep-Arvor profiling float






**Deep-Arvor: a deep profiling float « 100 % Argo compliant »**

Profile during ascent

Meas. available during descent

High resolution (4,000 CTD samples)

Continuous pumping

Spot sampling

Profile data transmitted within 48 hours

Ice Sensing Algorithm (ISA)

From seafloor to surface

Cost effective

Ascent & descent speed control

Reinforced grounding management

**100% Argo compliant**

DO available + in-air meas.

**150** CTD cycles

**200** CTD cycles

**4000** meters depth

**26 kg**

**PAYLOAD** capacity



**WAPIII Deep-Arvor**

- Deep-Arvor + ADCP
- Measurement of deep water masses currents in the Weddell sea (Antarctic)
- ADCP in bottom tracking mode





**3-heads Deep-Arvor**

- Deep-Arvor with Seabird 9801 CTD + Seabird 9801 CTD + RBR Concerto CTD
- In situ inter-comparison of CTDs:
  - Pressure dependency
  - Accuracy
  - Long-term stability
- Designed to embed more sensors



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# Poster session

28

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# Thank you for your attention!

## Questions?



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