Argo observation impact studies on ocean analysis and forecast at Mercator Ocean

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Mercator Ocean model configurations

- 1 single code : NEMO (LIM)
- 1 single grid : all the configurations are on the same ORCA (tripolar) grid
 1m vert sampling near the surface
- 1 single atmospheric forcing: based on ECMWF analysis and forecasts
- Some of these configurations are shared with the scientific community
 - ORCA025, ORCA12: DRAKKAR and GLORYS Projects

www.memo-ocean.eu and www.drakkar-ocean.eu



ORCA025 1/4° ORCA12 1/12° ATL12 1/12° NEATL36 1/36°



Mercator Ocean assimilation tool SAM2v1

- Based on a multivariate SEEK filter (Pham, 1998)
- Control vector is T, S, U, V, SSH (and sea ice concentration for reanalyses)
- Assimilated data

Along track altimetry (SLA from MyOcean: Jason-2, Cryosat-2, SARAL, HY-2A) SST maps (NOAA), T/S vertical profiles (From MyOcean, including ARGO)

Innovations are calculated using "3DFGAT"

forecast and observation are compared at the exact time and location of the observation

- 7-day assimilation window
- 3D forecast error covariances & localization
- Adaptive scheme for the first guess variance

First guess variance is adjusted at each assimilation cycle to be consistent with the innovation statistics (Tallagrand, 1998)

IAU (Incremental Analysis Update) scheme

Efficient way to smoothly restart the model. IAU is set for SSH, T, S, U, V

Bias correction on 3D T and S

Based on innovations of the last 3 month, variational (3D-var) large scale correction



Lellouche et al., Ocean Science (2013)

Mercator Ocean assimilation tool SAM2v1





Global forecasting system at 1/12°: assimilated observations

obs sla innovation : INNOV TRACK SLA on 11-03-2015



guess temperature innovation : SOFATINO on 11-03-2015 near 92m

E-aims project

Observing system experiment OSE



Impact of one given type of observations on the analysis (model+data assimilation) quality?

Withdraw one type of observations and compare with the reference analysis (assimilating all observations)

Argo OSEs with global 1/4° ocean system, year 2012

Run name	Assimilated data sets			
	SST AVHRR	SLA	Other INSITU	Argo INSITU
Run Ref	all	all	all	all
Run no argo	all	all	all	none
Run argo/2	all	all	all	50% only



Spatial distribution of 2012 *in-situ* dataset divided is 3 sub datasets. Red dots are the odd Argo profiles, blue dots are even Argo profiles, green dots are the other *in-situ* observations.



Argo OSE: innovation statistics

Impact of the current ARGO network on the global ¼° analysis system: simulation comparisons in terms of observation minus model forecast misfits for all in situ T,S data in 2012.

Reference run



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Global RMSE for 2012 in salinity and temperature

Argo OSE: residual statistics in temperature

Global RMS misfit between the in situ observations and OSEs analysis (last 6 months)









(hindcast-obs) RMS temperature : PSY3V3R3 700-2000m 2012



Run-NoArgo

Run-Argo/2

Run-Ref



Spatial distribution of the RMS temperature differences between Run-NoArgo / Run or Argo/2, Run-Ref and Argo observations in the 0-300m and 700-2000m layers

Argo OSE: residual statistics in salinity

Global RMS misfit between the in situ observations and OSEs analysis (last 6 months)

0-300m





(hindcast-obs) RMS salinity : PSY3V3R3 0-300m 2012



700-2000m



(hindcast-obs) RMS salinity : PSY3V3R3 700-2000m 2012



(hindcast-obs) RMS salinity : PSY3V3R3 700-2000m 2012



Run-Argo/2

Run-Ref



Run-NoArgo



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Conclusion of Argo OSE

The system reacts as we expected to the ARGO floats assimilation in terms of observation errors.

Regions of higher impact were highlighted:

- at depth, water masses from outflow or deep convection are better represented,
- in the surface layers, the largest impact is found in the tropical band and energetic ocean regions (WBC,...),
- keeping only half of the ARGO floats degrades significantly the analysis.



Vertical structure of RMS of temperature innovations (left) and normalized RMS temperature innovations (right) from 0-2000m for Run-Ref(blue), Run-Argo2(yellow), Run-NoArgo (green) and Free Run (red)





Impact of one given type of virtual observations on the analysis (model+data assimilation) quality?

Build a virtual dataset from a "nature run": model experiment at high resolution and as realistic as possible

Assimilate these virtual observations into a coarser model and assess their impact.



List of OSSEs experiments

	Argo down to 2000m	Argo down to 4000m	Argo down to ocean bottom
Run1 – Reference	all	none	none
Run2 – all 4000m	all	all	none
Run4 – 1/9 4000m	all	11%	none
Run3 - 1/9 bottom	all	11%	11%

Observation location for one week in october 2009 at 3200 m depth





1/3 of the floats are diving down to 4000 m depth each 3 profiles.

Argo OSSE: mean and RMS temperature innovations

global : Temperature Rms Misfit (region 0)



Down to 2000 m

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global : Temperature Rms Misfit (region 0

all down to 4000m

1/9 dive down to 4000 m

global : Temperature Rms Misfit (region 0)

1/9 down to 6000

global : Temperature Rms Misfit (

Global RMS and mean assimilated observation – model differences in temperature in the different OSSEs

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Argo OSSE: impact on analysed temperature

Mean temp. diff. 2000m-4000 m 🕛 Mean temp. diff. 4000m-6000 m

Run with Argo down to 2000 m

Run with 1/9 Argo down to 4000 m

Run with all Argo down to 4000 m





Mean deep ocean temperature misfits in °C between the "truth" and
different OSEs for different depth ranges.

OSSE experiments show:

- Increasing the depth of Argo floats profiles down to 4000 m depth instead of 2000m reduces the biais between 2000m down to the bottom where it was large,
- Increasing the depth of <u>only 1/9 Argo floats profiles down to 4000 m depth</u> instead of 2000m gives comparable results than if all are going down to 4000m. This is consistent with the fact that we found a low temporal variability but significant bias in some regions.
- Increasing the depth of Argo floats profiles down to 6000 m instead of 2000m for only 1/9 : analysis in progress.
- Ø The actual variability at depth <u>might be much smaller than the simulated model</u> <u>errors</u>, and there could be some issues detecting and controlling it.

Those conclusions are based on model simulation only.



Recommendations from Argo OSE/OSSE at Mercator Ocean

For Argo in situ observations, our system reacts as expected:

- The ¼° ocean forecast and analysis system is sensitive to the density change of the current Argo array,
- Solution Strategy Strategy Extending to depth the float profiles should allow the reduction of deep biases. A work has to be done to understand the small uniform bias appearing at depth.

Recommendations:

- The Argo array should be at least maintained at its present level of coverage and data quality.
- Deep ocean measurements are strongly required in data assimilative system. They are also crucial for model initialization (climatology), model validation and in situ/altimetry complementarity (contribution of the dynamic height deep ocean steric variability to SSH variability).

Deep argo measurement with a coarse resolution seems to be enough to constrain the deep bias of the ¼° ocean system.



Model and analysis validation

Glorys2v3: global number of in situ data and RMS innovations

Real time production validation: Observation misfit statistics 800m-2000m And 2000m-5000m







(hindcast-obs) MEAN salinity : PSY4V2R2 800-2000m 2014



(hindcast-obs) MEAN salinity : PSY4V2R2 2000-5000m 2014



global : Temperature Rms Misfit (region 0)



(hindcast-obs) MEAN temperature : PSY4V2R2 800-2000m 2014



(hindcast-obs) MEAN temperature : PSY4V2R2 2000-5000m 2014



Thank you for your attention!





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