Pushing Argo to the Limit

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Delayed-Mode Quality Control (DMQC)

Objectives

Good and bad data identified (Read the QC flags) Ensure consistent application of DMQC methods Provide uncertainty estimates 10 national DAC streams At least 20 groups performing DMQC

Series of DMQC workshops Apr 2005 First DMQC workshop Scripps Oct 2006 Second DMQC workshop WHOI Sep 2008 Third DMQC workshop U. Washington

Reports available at Coriolis web site

How do you know the DMQC status ?

Single profile names R1900292_100.nc D1900083_040.nc

DATA_MODE variable for each profile can be

- R real-time raw data
- A some adjustment has been applied, but not DMQC
- D profile has been assessed in DMQC

DMQC strategy

As far as possible check DATE and POSITION Look for spikes not detected by automatic methods

DMQC of TEMP

Very little we can do; TEMP assumed to be reliable unless there is obvious error Small TEMP errors hard to detect in variable ocean

DMQC of PSAL

Use statistical methods to compare T-S data from a float with 'reference data'

Based on differences decide that

- Float PSAL appears to be good
- Float PSAL is in error and should be adjusted to agree with reference
- Float PSAL may be in error, but adjusting to agree with reference is not correct
- Cannot determine whether float PSAL is good

Default assumption is float data need no adjustment unless statistical method clearly suggests otherwise

Statistical method provides an uncertainty estimate, generally determined by variability in reference data

Reference dataset

Based on holdings in World Ocean Database, edited and supplemented by Argo effortsMay be sparse: not enough data to evaluate floatMay be out of date: difference between float and reference is real Supplementing the reference database

Add recent CTDs from research cruises: issue of availability/timeliness New data critical to ensure Argo dataset can represent a changing ocean climate

Studying the implications of adding 'good' Argo data In data sparse regions, the number of Argo profiles dominates all 'historical' data

DMQC of PRES

Pressure sensor calibration can drift

Different platforms have different ways of measuring, reporting and allowing for sensor drift

- In recent sensors, drift is of order a few dbars (< 5) over lifetime of float
- Earlier models sometimes had drift of order 5 to 10 dbars, not random

Not all D floats have had consistent PRES adjustments applied: practice varies across DACs

Topics for discussion at DMQC-3

- Known patterns of instrument bias
- Statistical methods and tools for PSAL
- Consistency of application across DMQC groups
- **Regional variations**
- Reference data (include good Argo data or not ?)
- DMQC for PRES and TEMP
- Recording results of DMQC in NetCDF files

Conclusions on PRES, TEMP, PSAL For many applications, D-mode data are sufficient. Use

> <param>_ADJUSTED <param>_ADJUSTED_QC <param>_ADJUSTED_ERROR

When pushing right to the limit, it is necessary to consider carefully how the measurement is made, to understand the limitations of the QC process and to consider whether the data are appropriate for the application.